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IUTAM SYMPOSIUM ON OPTIMAL GUIDANCE AND CONTROL FOR AUTONOMOUS SYSTEMS

Derek Demeter (Emil Buehler Planetarium)

MARCH 19 - 21, 2020 UNIVERSITY OF HAWAI'I AT MĀNOA HONOLULU, HI, USA

Hawai'i is known around the world as an island paradise with beautiful beaches and clear blue skies. With these kind of conditions, Hawai'i provides an ideal location for developing and utilizing optimal guidance and control for autonomous systems with it's diverse terrain, that can also implemented in a vast amount of situations and uses around the world.

AREAS OF THE SYMPOSIUM INCLUDE, BUT ARE NOT LIMITED TO:

-MOTION PLANNING-STABILITY-OPTIMAL CONTROL AND GUIDANCE-TARGETING-FEEDBACK CONTROL-DATA PROCESSING-MACHINE LEARNING-SENSOR FUSION-SWARM NETWORK CONTROL-ON-BOARD CONTROL SYSTEMS AND-CENTRALIZIED OR DECENTRALIZED CONTROL-AUTONOMOUS GNC-GUIDANCE, NAVIGATION, AND CONTROL-AUTONOMOUS GNC

IMPORTANT DUE DATES:

AUGUST 26, 2019: ANNOUNCEMENT DECEMBER 31, 2019: ABSTRACT DUE JANUARY 10, 2020: ACCEPTANCE NOTIFICATION FEBRUARY 20, 2020: FINAL UPLOAD JANUARY 30 - FEBRUARY 20, 2020: EARLY REGISTRATION MARCH 19 - MARCH 20, 2020: ON-CITE REGISTRATION

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